

vm\_math Reference Manual  
1.0.5

Generated by Doxygen 1.4.2

Wed Apr 19 17:38:26 2006

## Contents

<a href="#">1 The vm_Math C++ template Library</a>	1
<a href="#">2 vm_math Module Index</a>	3
<a href="#">3 vm_math Directory Hierarchy</a>	4
<a href="#">4 vm_math Hierarchical Index</a>	4
<a href="#">5 vm_math Class Index</a>	5
<a href="#">6 vm_math Module Documentation</a>	5
<a href="#">7 vm_math Directory Documentation</a>	24
<a href="#">8 vm_math Class Documentation</a>	24

## 1 The vm\_Math C++ template Library

### 1.1 Copyright

**Author:**

Terry Gaetz

Copyright (C) 2006 Smithsonian Astrophysical Observatory

This file is part of vm\_math

vm\_math is free software; you can redistribute it and/or modify it under the terms of the GNU General Public License as published by the Free Software Foundation; either version 2 of the License, or (at your option) any later version.

vm\_Math is distributed in the hope that it will be useful, but WITHOUT ANY WARRANTY; without even the implied warranty of MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the GNU General Public License for more details.

You should have received a copy of the GNU General Public License along with this program; if not, write to the Free Software Foundation, Inc. 51 Franklin Street, Fifth Floor Boston, MA 02110-1301, USA

## 1.2 Overview

The `vm_math` C++ library is a collection of templated routines to deal efficiently with low-level floating point vectors, 3-vectors, and 3x3 matrices. It is split up into several sub-packages (see the **Modules** page for more information).

The `vm_math` package brings together a number of functions for operating on 3-vectors and 3-matrices, and for creating orthonormal 3-matrices corresponding to proper rotations (i.e., orthonormal matrices preserving the coordinate system parity).

These are implemented as inlined static member functions; the functions are bundled into classes in order to take them out of the global namespace. By making the functions static member functions, they can be called without recourse to an instantiated object, e.g.

```
double v1[] = { 1.3, 2.4, 7.2, 9.7 };
double v2[] = { 7.2, 1.9, 3.1, 4.1 };
double foo = vm_VMath<double,4>::dot( v2, v1 );
```

The package currently contains 3 classes:

- `vm_VMath<T_fp,N_len>`: common numerical operations on `N_len`-long one-dimensional arrays of floating point type `T_fp`. This class captures operations which do not depend on the explicit 3-vector or 3x3-matrix properties.
- `vm_V3math<T_fp>`: common numerical operations on 3-vectors of floating point type `T_fp`. Publicly derives from `vm_VMath<T_fp,3>`. This class adds in specifically 3-vector functionality such as vector cross products.
- `vm_M3math<T_fp>`: common numerical operations on 3x3 matrices of floating point type `T_fp`. The matrix is assumed to be stored as a contiguous one-dimensional array of 9 `T_fp`'s. Publicly derives from `vm_VMath<T_fp,9>`. This class adds in specifically matrix properties such as multiplication and matrix-vector multiplication.

All members are inlined, so the package consists only of header files.

### 1.3 `vm_VMath` common numerical operations

on `N_len`-long \* 1 dimensional arrays of `T_fp`

These routines provide the basic low-level support for 1-dimensional arrays of floating point values. The library is a C++ template library, with template parameters `T_fp` and `N_len`. `T_fp` is the floating point type. It must be a simple type (float or double), since it is assumed that the array can be copied as plain ol' data using `memcpy`. `N_len` is the dimension of the vector, assumed to be small, e.g., 9 for a flat representation of a 3x3 matrix. The class has no state information with all functionality implemented as (we hope) inlined functions.

To use these routines, ensure that you include the correct header file:

```
#include <vm_vmath/vm_vmath.h>
```

or

```
#include <vm_vmath/vm_math.h>
```

## 1.4 `vm_V3Math` common numerical operations

on 3-vectors of floating point values

These routines provide the basic low-level support for 3-vectors of floating point values of type `T_fp` (float or double). The library is a C++ template library, templated on `T_fp`.

To use these routines, ensure that you include the correct header file:

```
#include <vm_vmath/vm_v3math.h>
```

or

```
#include <vm_vmath/vm_math.h>
```

## 1.5 `vm_M3math` common numerical operations

on 3x3 matrices of floating point values

These routines provide the basic low-level support for 3x3 matrices of floating point values of type `T_fp` (float or double). The library is a C++ template library, templated on `T_fp`.

To use these routines, ensure that you include the correct header file:

```
#include <vm_vmath/vm_m3math.h>
```

or

```
#include <vm_vmath/vm_math.h>
```

# 2 `vm_math` Module Index

## 2.1 `vm_math` Modules

Here is a list of all modules:

<b>vm_VMath common numerical operations</b>	<b>5</b>
<b>vm_V3Math common numerical operations</b>	<b>5</b>
<b>vm_M3Math common numerical operations</b>	<b>5</b>
<b>Index calculations</b>	<b>5</b>
<b>Initialize a matrix.</b>	<b>6</b>
<b>For a matrix, insert or extract a vector.</b>	<b>7</b>
<b>Matrix Vector operations.</b>	<b>8</b>
<b>Matrix Matrix operations.</b>	<b>9</b>
<b>IO operations.</b>	<b>9</b>
<b>Set vector components</b>	<b>10</b>
<b>Normalize vectors</b>	<b>11</b>
<b>Tests for normality, orthogonality</b>	<b>12</b>
<b>Dot and Cross products.</b>	<b>13</b>
<b>IO operations.</b>	<b>14</b>
<b>Copy routines</b>	<b>15</b>
<b>Set functions</b>	<b>16</b>
<b>Componentwise op_eq operations (+=, -=, /=)</b>	<b>16</b>
<b>{add,sub,mul,div}: componentwise binary operations.</b>	<b>19</b>
<b>Linear combinations</b>	<b>22</b>
<b>I/O operations.</b>	<b>23</b>

## **3 vm\_math Directory Hierarchy**

### **3.1 vm\_math Directories**

This directory hierarchy is sorted roughly, but not completely, alphabetically:

<b>vm_math</b>	<b>24</b>
----------------	-----------

## 4 `vm_math` Hierarchical Index

### 4.1 `vm_math` Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

<a href="#">vm_VMath&lt; T_fp, N_len &gt;</a>	28
<a href="#">vm_VMath&lt; T_fp, 3 &gt;</a>	28
<a href="#">vm_V3Math&lt; T_fp &gt;</a>	26
<a href="#">vm_VMath&lt; T_fp, 9 &gt;</a>	28
<a href="#">vm_M3Math&lt; T_fp &gt;</a>	24

## 5 `vm_math` Class Index

### 5.1 `vm_math` Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">vm_M3Math&lt; T_fp &gt;</a>	24
<a href="#">vm_V3Math&lt; T_fp &gt;</a>	26
<a href="#">vm_VMath&lt; T_fp, N_len &gt;</a>	28

## 6 `vm_math` Module Documentation

### 6.1 `vm_VMath` common numerical operations

### 6.2 `vm_V3Math` common numerical operations

### 6.3 `vm_M3Math` common numerical operations

### 6.4 Index calculations

#### Functions

- `*static int vm_M3Math::at (int i, int j)`

### 6.4.1 Function Documentation

**6.4.1.1** `template<class T_fp> int vm_M3Math< T_fp >::at (int i, int j)`  
`[inline, static, inherited]`

Index calculation.

```
Array value m[i][j] is *(m + i*EColStride + j)
```

**Returns:**

offset of index set i, j (used for flat array storage)

**Parameters:**

*i* index

*j* index

Definition at line 290 of file vm\_m3math.h.

## 6.5 Initialize a matrix.

### Functions

- `*static void vm_M3Math::init_by_row` (`T_fp m[]`, `T_fp const row0[]`, `T_fp const row1[]`, `T_fp const row2[]`)
- `static void vm_M3Math::init_by_col` (`T_fp m[]`, `T_fp const col0[]`, `T_fp const col1[]`, `T_fp const col2[]`)
- `static void vm_M3Math::dyad_product` (`T_fp m[]`, `T_fp const v1[]`, `T_fp const v2[]`)

### 6.5.1 Function Documentation

**6.5.1.1** `template<class T_fp> void vm_M3Math< T_fp >::dyad_product (T_fp m[], T_fp const v1[], T_fp const v2[])`  
`[inline, static, inherited]`

Initialize a matrix to a dyadic (outer) product of vectors

For each i, j:  $m[at(i,j)] = v1[i] * v2[j]$

**Parameters:**

*m* matrix (as stored flat 1D array)

*v1* 1st vector

*v2* 2nd vector

Definition at line 361 of file vm\_m3math.h.

**6.5.1.2** `template<class T_fp> void vm_M3Math< T_fp >::init_by_col (T_fp m[], T_fp const col0[], T_fp const col1[], T_fp const col2[]) [inline, static, inherited]`

Initialize matrix by column; set columns of m to col0, col1, col2.

**Parameters:**

- m* matrix (as stored flat 1D array)
- col0* 1st column vector
- col1* 2nd column vector
- col2* 3rd column vector

Definition at line 308 of file vm\_m3math.h.

**6.5.1.3** `template<class T_fp> void vm_M3Math< T_fp >::init_by_row (T_fp m[], T_fp const row0[], T_fp const row1[], T_fp const row2[]) [inline, static, inherited]`

Initialize matrix by row; set rows of m to row0, row1, row2.

**Parameters:**

- m* matrix (as stored flat 1D array)
- row0* 1st row vector
- row1* 2nd row vector
- row2* 3rd row vector

Definition at line 298 of file vm\_m3math.h.

## 6.6 For a matrix, insert or extract a vector.

### Functions

- `*static void vm_M3Math::inject_row (T_fp m[], T_fp const row[], int whichrow)`
- `static void vm_M3Math::inject_col (T_fp m[], T_fp const col[], int whichcol)`
- `static void vm_M3Math::extract_row (T_fp const m[], T_fp row[], int whichrow)`
- `static void vm_M3Math::extract_col (T_fp const m[], T_fp col[], int whichcol)`

### 6.6.1 Function Documentation

**6.6.1.1** `template<class T_fp> void vm_M3Math< T_fp >::extract_col (T_fp const m[], T_fp col[], int whichcol)` [inline, static, inherited]

Copy a given column of m to a vector.

**Parameters:**

*m* matrix (as stored flat 1D array)

*col* vector to receive the copy

*whichcol* column index

Definition at line 347 of file vm\_m3math.h.

**6.6.1.2** `template<class T_fp> void vm_M3Math< T_fp >::extract_row (T_fp const m[], T_fp row[], int whichrow)` [inline, static, inherited]

Copy a given row of m to a vector.

**Parameters:**

*m* matrix (as stored flat 1D array)

*row* vector to receive the copy

*whichrow* row index

Definition at line 341 of file vm\_m3math.h.

**6.6.1.3** `template<class T_fp> void vm_M3Math< T_fp >::inject_col (T_fp m[], T_fp const col[], int whichcol)` [inline, static, inherited]

Copy a vector to a given column of m.

**Parameters:**

*m* matrix (as stored flat 1D array)

*col* vector to be stored

*whichcol* column index

Definition at line 327 of file vm\_m3math.h.

**6.6.1.4** `template<class T_fp> void vm_M3Math< T_fp >::inject_row (T_fp m[], T_fp const row[], int whichrow)` [inline, static, inherited]

Copy a vector to a given row of m.

**Parameters:**

- m* matrix (as stored flat 1D array)
- row* vector to be stored
- whichrow* row index

Definition at line 321 of file vm\_m3math.h.

**6.7 Matrix Vector operations.****Functions**

- \*static void [vm\\_M3Math::mvmult](#) (T\_fp res[ ], T\_fp const m[ ], T\_fp const v[ ])
- static void [vm\\_M3Math::mtvmult](#) (T\_fp res[ ], T\_fp const m[ ], T\_fp const v[ ])

**6.7.1 Function Documentation**

**6.7.1.1** `template<class T_fp> void vm\_M3Math<T_fp>::mtvmult (T_fp res[ ], T_fp const m[ ], T_fp const v[ ]) [inline, static, inherited]`

Matrix multiplication of vector *v* by transpose of matrix *m*.

result = m\_transpose\_matrix\_multiply\_ v.

**Parameters:**

- res* resulting matrix (as stored flat 1D array)
- m* matrix to be transposed and multiplied
- v* vector to be multiplied

Definition at line 382 of file vm\_m3math.h.

**6.7.1.2** `template<class T_fp> void vm\_M3Math<T_fp>::mvmult (T_fp res[ ], T_fp const m[ ], T_fp const v[ ]) [inline, static, inherited]`

Matrix multiplication of vector *v* by matrix *m*.

result = m\_matrix\_multiply\_ v.

**Parameters:**

- res* resulting matrix (as stored flat 1D array)
- m* matrix to be multiplied
- v* vector to be multiplied

Definition at line 373 of file vm\_m3math.h.

## 6.8 Matrix Matrix operations.

### Functions

- `*static void mmult (T_fp mres[ ], T_fp const m1[ ], T_fp const m2[ ])`

## 6.9 IO operations.

### Functions

- `*static std::ostream & vm_M3Math::print_on (std::ostream &os, T_fp const m[ ], char const prefix[ ]="", char const postfix[ ]="")`
- `static void vm_M3Math::cprint_on (FILE *of, T_fp const m[ ], char const prefix[ ]="", char const postfix[ ]="")`

### 6.9.1 Function Documentation

**6.9.1.1** `template<class T_fp> void vm_M3Math< T_fp >::cprint_on (FILE * of, T_fp const m[ ], char const prefix[ ] = "", char const postfix[ ] = "")` [inline, static, inherited]

Print a matrix to a FILE\* stream.

#### Parameters:

- of* the FILE\*
- m* matrix to be printed
- prefix* optional prefix string
- postfix* optional postfix string

Definition at line 421 of file vm\_m3math.h.

**6.9.1.2** `template<class T_fp> std::ostream & vm_M3Math< T_fp >::print_on (std::ostream & os, T_fp const m[ ], char const prefix[ ] = "", char const postfix[ ] = "")` [inline, static, inherited]

Print a matrix to an ostream.

#### Parameters:

- os* the ostream
- m* matrix to be printed
- prefix* optional prefix string
- postfix* optional postfix string

Definition at line 408 of file vm\_m3math.h.

## 6.10 Set vector components

### Functions

- `*static void vm\_V3Math::set (T_fp v[], T_fp x, T_fp y, T_fp z)`
- `static void vm\_V3Math::set (T_fp v[], T_fp x)`

### 6.10.1 Function Documentation

**6.10.1.1** `template<class T_fp> void vm\_V3Math< T_fp >::set (T_fp v[], T_fp x)` [`inline`, `static`, `inherited`]

Set all components of `v` to `x`.

#### Parameters:

- `v` vector to be set
- `x` value

Reimplemented from `vm\_VMath< T_fp, 3 >`.

Definition at line 260 of file `vm_v3math.h`.

References `vm\_VMath< T_fp, N_len >::set()`.

**6.10.1.2** `template<class T_fp> void vm\_V3Math< T_fp >::set (T_fp v[], T_fp x, T_fp y, T_fp z)` [`inline`, `static`, `inherited`]

Set components of `v` to `x`, `y`, `z`.

#### Parameters:

- `v` vector to be set
- `x` x component
- `y` y component
- `z` z component

Definition at line 255 of file `vm_v3math.h`.

## 6.11 Normalize vectors

### Functions

- `*static T_fp vm\_V3Math::unitize (T_fp v[])`
- `static T_fp vm\_V3Math::unitize (T_fp vu[], T_fp const vi[])`

### 6.11.1 Function Documentation

**6.11.1.1** `template<class T_fp> T_fp vm\_V3Math< T_fp >::unitize (T_fp vu [, T_fp const vi])` [inline, static, inherited]

Normalize a vector *vi* returning the normalized value in *vu*.

**Returns:**

return original magnitude of *vi*

**Parameters:**

*vi* vector to be normalized

*vu* normalized version of *vi*

Definition at line 296 of file `vm_v3math.h`.

References `vm_VMath< T_fp, 3 >::copy()`, and `vm_V3Math< T_fp >::unitize()`.

**6.11.1.2** `template<class T_fp> T_fp vm\_V3Math< T_fp >::unitize (T_fp v[])` [inline, static, inherited]

Normalize a vector *v*.

**Returns:**

return original vector magnitude

**Parameters:**

*v* vector to be normalized

Definition at line 282 of file `vm_v3math.h`.

References `vm_VMath< T_fp, 3 >::div_eq()`, and `vm_V3Math< T_fp >::dot()`.

Referenced by `vm_V3Math< T_fp >::unitize()`.

## 6.12 Tests for normality, orthogonality

### Functions

- `*static int vm\_V3Math::is\_unit\_vector (T_fp const v[], T_fp const tol)`
- `static int vm\_V3Math::are\_orthogonal (T_fp const v[], T_fp const other[], T_fp const tol)`
- `static int vm\_V3Math::are\_orthonormal (T_fp const v[], T_fp const other[], T_fp const tol)`

### 6.12.1 Function Documentation

**6.12.1.1** `template<class T_fp> int vm_V3Math< T_fp >::are_orthogonal (T_fp const v[], T_fp const other[], T_fp const tol) [inline, static, inherited]`

Test whether a *v* is within tolerance *tol* of orthogonality to other vector

**Returns:**

1 if *v* and *other* are orthogonal within tolerance *tol*, 0 otherwise.

**Parameters:**

*v* vector to be checked

*other* other vector

*tol* tolerance

Definition at line 311 of file `vm_v3math.h`.

References `vm_V3Math< T_fp >::dot()`.

Referenced by `vm_V3Math< T_fp >::are_orthonormal()`.

**6.12.1.2** `template<class T_fp> int vm_V3Math< T_fp >::are_orthonormal (T_fp const v[], T_fp const other[], T_fp const tol) [inline, static, inherited]`

Test whether *v* is within tolerance *tol* of orthonormality with other vector

**Returns:**

1 if *v* and *other* are orthonormal within tolerance *tol*, 0 otherwise.

**Parameters:**

*v* vector to be checked

*other* other vector

*tol* tolerance

Definition at line 320 of file `vm_v3math.h`.

References `vm_V3Math< T_fp >::are_orthogonal()`, and `vm_V3Math< T_fp >::is_unit_vector()`.

**6.12.1.3** `template<class T_fp> int vm_V3Math< T_fp >::is_unit_vector (T_fp const v[], T_fp const tol) [inline, static, inherited]`

Test whether a vector is within tolerance *tol* of a unit vector

**Returns:**

1 if  $v$  is within tolerance  $tol$  of being a unit vector, 0 otherwise.

**Parameters:**

$v$  vector to be checked

$tol$  tolerance

Definition at line 304 of file `vm_v3math.h`.

References `vm_V3Math< T_fp >::dot()`.

Referenced by `vm_V3Math< T_fp >::are_orthonormal()`.

**6.13 Dot and Cross products.****Functions**

- `*static T_fp vm_V3Math::dot (T_fp const v1[], T_fp const v2[])`
- `static void vm_V3Math::cross (T_fp prod[], T_fp const v1[], T_fp const v2[])`

**6.13.1 Function Documentation**

**6.13.1.1** `template<class T_fp> void vm_V3Math< T_fp >::cross (T_fp prod[], T_fp const v1[], T_fp const v2[])` [`inline`, `static`, `inherited`]

Cross (wedge) product of two vectors

**Returns:**

cross (wedge) product of  $v1$  with  $v2$ .

**Parameters:**

$prod$  cross (wedge) product of  $v1$  with  $v2$ .

$v1$  1st vector

$v2$  2nd vector

Definition at line 272 of file `vm_v3math.h`.

**6.13.1.2** `template<class T_fp> T_fp vm_V3Math< T_fp >::dot (T_fp const v1[], T_fp const v2[])` [`inline`, `static`, `inherited`]

Dot product of two vectors

**Returns:**

dot (scalar) product of  $v1$  with  $v2$ .

**Parameters:***v1* 1st vector*v2* 2nd vectorDefinition at line 265 of file `vm_v3math.h`.Referenced by `vm_V3Math< T_fp >::are_orthogonal()`, `vm_V3Math< T_fp >::is_unit_vector()`, and `vm_V3Math< T_fp >::unitize()`.**6.14 IO operations.****Functions**

- `*static std::ostream & vm_V3Math::print_on` (`std::ostream &os`, `T_fp const v[]`, `char const prefix[]=""`, `char const postfix[]=""`)
- `static void vm_V3Math::cprint_on` (`FILE *of`, `T_fp const v[]`, `char const prefix[]=""`, `char const postfix[]=""`)

**6.14.1 Function Documentation**

**6.14.1.1** `template<class T_fp> void vm_V3Math< T_fp >::cprint_on` (`FILE *of`, `T_fp const v[]`, `char const prefix[]=""`, `char const postfix[]=""`) [`inline`, `static`, `inherited`]

Print a vector to a FILE\* stream.

**Parameters:***of* the FILE\**v* vector to be printed*prefix* optional prefix string*postfix* optional postfix stringDefinition at line 340 of file `vm_v3math.h`.

**6.14.1.2** `template<class T_fp> std::ostream & vm_V3Math< T_fp >::print_on` (`std::ostream & os`, `T_fp const v[]`, `char const prefix[]=""`, `char const postfix[]=""`) [`inline`, `static`, `inherited`]

Print a vector to an ostream.

**Parameters:***os* the ostream*v* vector to be printed

*prefix* optional prefix string  
*postfix* optional postfix string

Definition at line 331 of file vm\_v3math.h.

## 6.15 Copy routines

### Functions

- `*static void vm_VMath::copy (T_fp v[], T_fp const cv[])`

#### 6.15.1 Function Documentation

**6.15.1.1** `template<class T_fp, int N_len> void vm_VMath< T_fp, N_len >::copy (T_fp v[], T_fp const cv[])` [`inline, static, inherited`]

Normalize a vector *v*.

#### Parameters:

- v* destination vector
- cv* source vector

REQUIREMENT: *\*v* and *\*cv* each has a length of at least *N\_len* contiguous *T\_fps* and is appropriately aligned for *T\_fps*.

Definition at line 385 of file vm\_vmath.h.

## 6.16 Set functions

### Functions

- `*static void vm_VMath::set (T_fp v[], T_fp r)`

#### 6.16.1 Function Documentation

**6.16.1.1** `template<class T_fp, int N_len> void vm_VMath< T_fp, N_len >::set (T_fp v[], T_fp r)` [`inline, static, inherited`]

Set all elements of *v* to *r*.

#### Parameters:

- v* vector to be set
- r* value

Reimplemented in `vm_V3Math< T_fp >`.

Definition at line 393 of file `vm_vmATH.h`.

Referenced by `vm_V3Math< T_fp >::set()`.

## 6.17 Componentwise op\_eq operations (+=, -=, /=)

### Functions

- `*static void vm_VMath::add_eq (T_fp v[], T_fp const cv[])`
- `static void vm_VMath::sub_eq (T_fp v[], T_fp const cv[])`
- `static void vm_VMath::mul_eq (T_fp v[], T_fp const cv[])`
- `static void vm_VMath::div_eq (T_fp v[], T_fp const cv[])`
- `static void vm_VMath::add_eq (T_fp v[], T_fp r)`
- `static void vm_VMath::sub_eq (T_fp v[], T_fp r)`
- `static void vm_VMath::mul_eq (T_fp v[], T_fp r)`
- `static void vm_VMath::div_eq (T_fp v[], T_fp r)`
- `static void vm_VMath::negate (T_fp v[])`

### 6.17.1 Function Documentation

**6.17.1.1** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::add_eq (T_fp v[], T_fp r)` [`inline, static, inherited`]

component-wise  $v[n] += r$

#### Parameters:

- `v` LHS vector
- `r` RHS `T_fp`

**6.17.1.2** `template<class T_fp, int N_len> *static void vm_VMath< T_fp, N_len >::add_eq (T_fp v[], T_fp const cv[])` [`inline, static, inherited`]

component-wise  $v[n] += cv[n]$

#### Parameters:

- `v` LHS vector
- `cv` RHS vector

**6.17.1.3** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::div_eq (T_fp v[], T_fp r)` [inline, static, inherited]

component-wise  $v[n] /= r$

**Parameters:**

$v$  LHS vector

$r$  RHS T\_fp

**6.17.1.4** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::div_eq (T_fp v[], T_fp const cv[])` [inline, static, inherited]

component-wise  $v[n] /= cv[n]$

**Parameters:**

$v$  LHS vector

$cv$  RHS vector

**6.17.1.5** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::mul_eq (T_fp v[], T_fp r)` [inline, static, inherited]

component-wise  $v[n] *= r$

**Parameters:**

$v$  LHS vector

$r$  RHS T\_fp

**6.17.1.6** `template<class T_fp, int N_len> static void vm_VMath< T_fp, N_len >::mul_eq (T_fp v[], T_fp const cv[])` [inline, static, inherited]

component-wise  $v[n] *= cv[n]$

**Parameters:**

$v$  LHS vector

$cv$  RHS vector

**6.17.1.7** `template<class T_fp, int N_len> int N_len void vm_VMath< T_fp, N_len >::negate (T_fp v[])` [inline, static, inherited]

component-wise negation of  $v$

**Parameters:**

$v$  vector

Definition at line 414 of file `vm_vmh.h`.

**6.17.1.8** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::sub_eq (T_fp v[], T_fp r)` [inline, static, inherited]

component-wise  $v[n] -= r$

**Parameters:**

- v* LHS vector
- r* RHS T\_fp

**6.17.1.9** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::sub_eq (T_fp v[], T_fp const cv[])` [inline, static, inherited]

component-wise  $v[n] -= cv[n]$

**Parameters:**

- v* LHS vector
- cv* RHS vector

## 6.18 {add,sub,mul,div}: componentwise binary operations.

### Functions

- \*static void [vm\\_VMath::add](#) (T\_fp v[], T\_fp const cv1[], T\_fp const cv2[])
- static void [vm\\_VMath::sub](#) (T\_fp v[], T\_fp const cv1[], T\_fp const cv2[])
- static void [vm\\_VMath::mul](#) (T\_fp v[], T\_fp const cv1[], T\_fp const cv2[])
- static void [vm\\_VMath::div](#) (T\_fp v[], T\_fp const cv1[], T\_fp const cv2[])
- static void [vm\\_VMath::add](#) (T\_fp v[], T\_fp const cv[], T\_fp r)
- static void [vm\\_VMath::sub](#) (T\_fp v[], T\_fp const cv[], T\_fp r)
- static void [vm\\_VMath::mul](#) (T\_fp v[], T\_fp const cv[], T\_fp r)
- static void [vm\\_VMath::div](#) (T\_fp v[], T\_fp const cv[], T\_fp r)
- static void [vm\\_VMath::add](#) (T\_fp v[], T\_fp r, T\_fp const cv[])
- static void [vm\\_VMath::sub](#) (T\_fp v[], T\_fp r, T\_fp const cv[])
- static void [vm\\_VMath::mul](#) (T\_fp v[], T\_fp r, T\_fp const cv[])
- static void [vm\\_VMath::div](#) (T\_fp v[], T\_fp r, T\_fp const cv[])

### 6.18.1 Function Documentation

**6.18.1.1** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::add (T_fp v[], T_fp r, T_fp const cv[])` [inline, static, inherited]

component-wise  $v[n] = r + cv[n]$

**Parameters:**

*v* result vector  
*r* input T\_fp  
*cv* input vector

**6.18.1.2** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::add (T_fp v[], T_fp const cv[], T_fp r) [inline, static, inherited]`

component-wise  $v[n] = cv[n] + r$

**Parameters:**

*v* result vector  
*cv* input vector  
*r* input T\_fp

**6.18.1.3** `template<class T_fp, int N_len> * static void vm\_VMath< T_fp, N_len >::add (T_fp v[], T_fp const cv1[], T_fp const cv2[]) [inline, static, inherited]`

component-wise  $v[n] = cv1[n] + cv2[n]$

**Parameters:**

*v* result vector  
*cv1* 1st input vector  
*cv2* 2nd input vector

**6.18.1.4** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::div (T_fp v[], T_fp r, T_fp const cv[]) [inline, static, inherited]`

component-wise  $v[n] = r / cv[n]$

**Parameters:**

*v* result vector  
*r* input T\_fp  
*cv* input vector

**6.18.1.5** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::div (T_fp v[], T_fp const cv[], T_fp r)` [`inline, static, inherited`]

component-wise  $v[n] = cv[n] / r$

**Parameters:**

*v* result vector  
*cv* input vector  
*r* input T\_fp

**6.18.1.6** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::div (T_fp v[], T_fp const cv1[], T_fp const cv2[])` [`inline, static, inherited`]

component-wise  $v[n] = cv1[n] / cv2[n]$

**Parameters:**

*v* result vector  
*cv1* 1st input vector  
*cv2* 2nd input vector

**6.18.1.7** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::mul (T_fp v[], T_fp r, T_fp const cv[])` [`inline, static, inherited`]

component-wise  $v[n] = r * cv[n]$

**Parameters:**

*v* result vector  
*r* input T\_fp  
*cv* input vector

**6.18.1.8** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::mul (T_fp v[], T_fp const cv[], T_fp r)` [`inline, static, inherited`]

component-wise  $v[n] = cv[n] * r$

**Parameters:**

*v* result vector  
*cv* input vector  
*r* input T\_fp

**6.18.1.9** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::mul (T_fp v[], T_fp const cv1[], T_fp const cv2[]) [inline, static, inherited]`

component-wise  $v[n] = cv1[n] * cv2[n]$

**Parameters:**

- v* result vector
- cv1* 1st input vector
- cv2* 2nd input vector

**6.18.1.10** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::sub (T_fp v[], T_fp r, T_fp const cv[]) [inline, static, inherited]`

component-wise  $v[n] = r - cv[n]$

**Parameters:**

- v* result vector
- r* input T\_fp
- cv* input vector

**6.18.1.11** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::sub (T_fp v[], T_fp const cv[], T_fp r) [inline, static, inherited]`

component-wise  $v[n] = cv[n] - r$

**Parameters:**

- v* result vector
- cv* input vector
- r* input T\_fp

**6.18.1.12** `template<class T_fp, int N_len> static void vm\_VMath< T_fp, N_len >::sub (T_fp v[], T_fp const cv1[], T_fp const cv2[]) [inline, static, inherited]`

component-wise  $v[n] = cv1[n] - cv2[n]$

**Parameters:**

- v* result vector
- cv1* 1st input vector
- cv2* 2nd input vector

## 6.19 Linear combinations

### Functions

- \*static void `vm_VMath::lincomb` (T\_fp res[], T\_fp c1, T\_fp const v1[], T\_fp c2, T\_fp const v2[])

#### 6.19.1 Function Documentation

**6.19.1.1** `template<class T_fp, int N_len> void vm_VMath< T_fp, N_len >::lincomb` (T\_fp res[], T\_fp c1, T\_fp const v1[], T\_fp c2, T\_fp const v2[]) [inline, static, inherited]

form linear combination:  $res = c1 * v1 + c2 * v2$ .

For each  $i$ :  $res[i] = c1 * v1[i] + c2 * v2[i]$

#### Parameters:

- res* result vector
- c1* 1st T\_fp
- v1* 1st vector
- c2* 2nd T\_fp
- v2* 2nd vector

Definition at line 441 of file `vm_vmath.h`.

## 6.20 I/O operations.

### Functions

- \*static `std::ostream & vm_VMath::print_on` (`std::ostream &os`, T\_fp const v[], int by, char const prefix[]="", char const postfix[]="")
- static void `vm_VMath::cprint_on` (FILE \*of, T\_fp const v[], int by, char const prefix[]="", char const postfix[]="")

#### 6.20.1 Function Documentation

**6.20.1.1** `template<class T_fp, int N_len> void vm_VMath< T_fp, N_len >::cprint_on` (FILE \* of, T\_fp const v[], int by, char const prefix[] = "", char const postfix[] = "") [inline, static, inherited]

Print a vector to a FILE\* stream.

**Parameters:**

- of* the FILE\*
- v* vector to be printed
- by* stride by this many
- prefix* optional prefix string
- postfix* optional postfix string

Definition at line 471 of file `vm_vmath.h`.

**6.20.1.2** `template<class T_fp, int N_len> std::ostream & vm\_VMath< T_fp, N_len >::print_on (std::ostream & os, T_fp const v[], int by, char const prefix [] = "", char const postfix [] = "")` [`inline, static, inherited`]

Print a vector to an ostream.

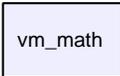
**Parameters:**

- os* the ostream
- v* vector to be printed
- by* stride by this many
- prefix* optional prefix string
- postfix* optional postfix string

Definition at line 451 of file `vm_vmath.h`.

## 7 `vm_math` Directory Documentation

### 7.1 `vm_math/` Directory Reference



`vm_math`

**Files**

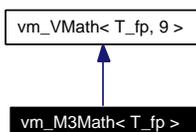
- file `vm_m3math.cc`
- file `vm_m3math.h`
- file `vm_math.h`
- file `vm_v3math.h`
- file `vm_vmath.h`

## 8 vm\_math Class Documentation

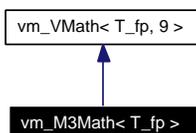
### 8.1 vm\_M3Math< T\_fp > Class Template Reference

```
#include <vm_math/vm_m3math.h>
```

Inheritance diagram for vm\_M3Math< T\_fp >:



Collaboration diagram for vm\_M3Math< T\_fp >:



#### Public Types

- typedef T\_fp **value\_type**

#### Static Public Member Functions

- \*static int **at** (int i, int j)
- \*static void **init\_by\_row** (T\_fp m[ ], T\_fp const row0[ ], T\_fp const row1[ ], T\_fp const row2[ ])
- static void **init\_by\_col** (T\_fp m[ ], T\_fp const col0[ ], T\_fp const col1[ ], T\_fp const col2[ ])
- static void **dyad\_product** (T\_fp m[ ], T\_fp const v1[ ], T\_fp const v2[ ])
- \*static void **inject\_row** (T\_fp m[ ], T\_fp const row[ ], int whichrow)
- static void **inject\_col** (T\_fp m[ ], T\_fp const col[ ], int whichcol)
- static void **extract\_row** (T\_fp const m[ ], T\_fp row[ ], int whichrow)
- static void **extract\_col** (T\_fp const m[ ], T\_fp col[ ], int whichcol)
- \*static void **mvmult** (T\_fp res[ ], T\_fp const m[ ], T\_fp const v[ ])
- static void **mtvmult** (T\_fp res[ ], T\_fp const m[ ], T\_fp const v[ ])
- \*static void **mmult** (T\_fp mres[ ], T\_fp const m1[ ], T\_fp const m2[ ])
- \*static std::ostream & **print\_on** (std::ostream &os, T\_fp const m[ ], char const prefix[ ]="", char const postfix[ ]="")

- static void `cprint_on` (FILE \*of, T\_fp const m[], char const prefix[]="", char const postfix[]="")

### 8.1.1 Detailed Description

`template<class T_fp> class vm_M3Math< T_fp >`

A template class providing common numerical operations on 3x3-matrices of T\_fp's (floating point type). The matrix is assumed to be stored as a \* contiguous one-dimensional array of 9 T\_fp's, properly aligned for type T\_fp.

The class is a simple class to handle common numerical operations on 3x3-matrices of floating point T\_fps.

Unless otherwise noted, the operations are component by component, e.g.,

```
mul_eq(m1,m2)
```

results in

```
m1[i][j] += m2[i][j], where i = 0,1,2 and j = 0,1,2.
```

`vm_M3Math` has only static member functions; there are no data members.

Where possible, the static member functions are inlined.

Definition at line 77 of file `vm_m3math.h`.

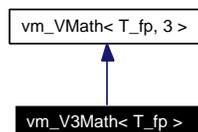
The documentation for this class was generated from the following file:

- `vm_m3math.h`

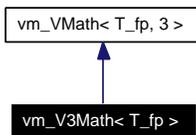
## 8.2 `vm_V3Math< T_fp >` Class Template Reference

```
#include <vm_math/vm_v3math.h>
```

Inheritance diagram for `vm_V3Math< T_fp >`:



Collaboration diagram for `vm_V3Math< T_fp >`:



### Public Types

- typedef `T_fp` `value_type`

### Static Public Member Functions

- \*static void `set` (`T_fp` `v[ ]`, `T_fp` `x`, `T_fp` `y`, `T_fp` `z`)
- static void `set` (`T_fp` `v[ ]`, `T_fp` `x`)
- \*static `T_fp` `unitize` (`T_fp` `v[ ]`)
- static `T_fp` `unitize` (`T_fp` `vu[ ]`, `T_fp` const `vi[ ]`)
- \*static int `is_unit_vector` (`T_fp` const `v[ ]`, `T_fp` const `tol`)
- static int `are_orthogonal` (`T_fp` const `v[ ]`, `T_fp` const `other[ ]`, `T_fp` const `tol`)
- static int `are_orthonormal` (`T_fp` const `v[ ]`, `T_fp` const `other[ ]`, `T_fp` const `tol`)
- \*static `T_fp` `dot` (`T_fp` const `v1[ ]`, `T_fp` const `v2[ ]`)
- static void `cross` (`T_fp` `prod[ ]`, `T_fp` const `v1[ ]`, `T_fp` const `v2[ ]`)
- \*static `std::ostream &` `print_on` (`std::ostream &os`, `T_fp` const `v[ ]`, `char` const `prefix[ ]`="", `char` const `postfix[ ]`="")
- static void `cprint_on` (`FILE *of`, `T_fp` const `v[ ]`, `char` const `prefix[ ]`="", `char` const `postfix[ ]`="")

#### 8.2.1 Detailed Description

`template<class T_fp> class vm_V3Math< T_fp >`

A template class providing common numerical operations on 3-vectors of `T_fp`'s (floating point type).

Unless otherwise noted, the operations are component by component, e.g.,

```
vm_V3Mathlt<float>::div_eq(v1, v2)
```

corresponds to

```
v1[i] /= v2[i], where i = 0,1,2.
```

`vm_V3Math` has only static member functions; there are no data members.

Where possible, the static member functions are inlined.

Definition at line 69 of file `vm_v3math.h`.

## 8.2.2 Member Typedef Documentation

### 8.2.2.1 `template<class T_fp> vm_V3Math< T_fp >::value_type`

A typedef for the floating point type;

Reimplemented from `vm_VMath< T_fp, 3 >`.

Definition at line 83 of file `vm_v3math.h`.

The documentation for this class was generated from the following file:

- `vm_v3math.h`

## 8.3 `vm_VMath< T_fp, N_len >` Class Template Reference

```
#include <vm_math/vm_vmath.h>
```

### Public Types

- typedef `T_fp` `value_type`

### Static Public Member Functions

- `*static void copy` (`T_fp v[]`, `T_fp const cv[]`)
- `*static void set` (`T_fp v[]`, `T_fp r`)
- `*static void add_eq` (`T_fp v[]`, `T_fp const cv[]`)
- `static void sub_eq` (`T_fp v[]`, `T_fp const cv[]`)
- `static void mul_eq` (`T_fp v[]`, `T_fp const cv[]`)
- `static void div_eq` (`T_fp v[]`, `T_fp const cv[]`)
- `static void add_eq` (`T_fp v[]`, `T_fp r`)
- `static void sub_eq` (`T_fp v[]`, `T_fp r`)
- `static void mul_eq` (`T_fp v[]`, `T_fp r`)
- `static void div_eq` (`T_fp v[]`, `T_fp r`)
- `static void negate` (`T_fp v[]`)
- `*static void add` (`T_fp v[]`, `T_fp const cv1[]`, `T_fp const cv2[]`)
- `static void sub` (`T_fp v[]`, `T_fp const cv1[]`, `T_fp const cv2[]`)
- `static void mul` (`T_fp v[]`, `T_fp const cv1[]`, `T_fp const cv2[]`)
- `static void div` (`T_fp v[]`, `T_fp const cv1[]`, `T_fp const cv2[]`)

- static void `add` (`T_fp v[]`, `T_fp const cv[]`, `T_fp r`)
- static void `sub` (`T_fp v[]`, `T_fp const cv[]`, `T_fp r`)
- static void `mul` (`T_fp v[]`, `T_fp const cv[]`, `T_fp r`)
- static void `div` (`T_fp v[]`, `T_fp const cv[]`, `T_fp r`)
- static void `add` (`T_fp v[]`, `T_fp r`, `T_fp const cv[]`)
- static void `sub` (`T_fp v[]`, `T_fp r`, `T_fp const cv[]`)
- static void `mul` (`T_fp v[]`, `T_fp r`, `T_fp const cv[]`)
- static void `div` (`T_fp v[]`, `T_fp r`, `T_fp const cv[]`)
- \*static void `lincomb` (`T_fp res[]`, `T_fp c1`, `T_fp const v1[]`, `T_fp c2`, `T_fp const v2[]`)
- \*static `std::ostream & print_on` (`std::ostream &os`, `T_fp const v[]`, `int by`, `char const prefix[]`="", `char const postfix[]`="")
- static void `cprint_on` (`FILE *of`, `T_fp const v[]`, `int by`, `char const prefix[]`="", `char const postfix[]`="")

### 8.3.1 Detailed Description

**template<class T\_fp, int N\_len> class vm\_VMath< T\_fp, N\_len >**

A template class providing common numerical operations on `N_len`-long 1 dimensional arrays of `T_fp`.

`T_fp` is a floating point type.

`N_len` is the length of the vector.

The array data are assumed to be stored as a contiguous one-dimensional array of `N_len` `T_fp`'s, properly aligned for type `T_fp`.

Unless otherwise noted, the operations are component by component, e.g.,

```
vm_VMath<float,4>::mul(prod, v1, v2)
```

corresponds to

```
prod[i] = v1[i] * v2[i], where i = 0,1,2,3.
```

`vm_VMath` has only static member functions; there are no data members.

Where possible, the static member functions are inlined.

Definition at line 78 of file `vm_vmath.h`.

### 8.3.2 Member Typedef Documentation

#### 8.3.2.1 `template<class T_fp, int N_len> vm_VMath< T_fp, N_len >::value_type`

a typedef for the floating point type;

Reimplemented in `vm_V3Math< T_fp >`.

Definition at line 91 of file `vm_vmath.h`.

The documentation for this class was generated from the following file:

- `vm_vmath.h`

## Index

- {add,sub,mul,div}: componentwise binary operations., 19
- add
  - ndvec\_mathop, 19
- add\_eq
  - ndvec\_opeq, 17
- are\_orthogonal
  - vec\_test\_norm, 12
- are\_orthonormal
  - vec\_test\_norm, 12
- at
  - mat\_index\_calculations, 5
- Componentwise op\_eq operations (+, -, =, /=), 16
- copy
  - ndvec\_copy, 15
- Copy routines, 15
- cprint\_on
  - mat\_io, 10
  - ndvec\_io, 23
  - vec\_io, 15
- cross
  - vec\_dot\_cross, 14
- div
  - ndvec\_mathop, 20
- div\_eq
  - ndvec\_opeq, 17
- dot
  - vec\_dot\_cross, 14
- Dot and Cross products., 13
- dyad\_product
  - mat\_init, 6
- extract\_col
  - mat\_insert\_extract, 7
- extract\_row
  - mat\_insert\_extract, 7
- For a matrix, insert or extract a vector., 7
- I/O operations., 23
- Index calculations, 5
- init\_by\_col
  - mat\_init, 6
- init\_by\_row
  - mat\_init, 6
- Initialize a matrix., 6
- inject\_col
  - mat\_insert\_extract, 8
- inject\_row
  - mat\_insert\_extract, 8
- IO operations., 9, 14
- is\_unit\_vector
  - vec\_test\_norm, 13
- lincomb
  - ndvec\_lincomb, 22
- Linear combinations, 22
- mat\_index\_calculations
  - at, 5
- mat\_init
  - dyad\_product, 6
  - init\_by\_col, 6
  - init\_by\_row, 6
- mat\_insert\_extract
  - extract\_col, 7
  - extract\_row, 7
  - inject\_col, 8
  - inject\_row, 8
- mat\_io
  - cprint\_on, 10
  - print\_on, 10
- mat\_vec\_ops
  - mtvmult, 9
  - mvmult, 9
- Matrix Matrix operations., 9
- Matrix Vector operations., 8
- mtvmult
  - mat\_vec\_ops, 9
- mul
  - ndvec\_mathop, 20, 21
- mul\_eq

- ndvec\_opeq, [17, 18](#)
- mvmult
  - mat\_vec\_ops, [9](#)
- ndvec\_copy
  - copy, [15](#)
- ndvec\_io
  - cprint\_on, [23](#)
  - print\_on, [23](#)
- ndvec\_lincomb
  - lincomb, [22](#)
- ndvec\_mathop
  - add, [19](#)
  - div, [20](#)
  - mul, [20, 21](#)
  - sub, [21, 22](#)
- ndvec\_opeq
  - add\_eq, [17](#)
  - div\_eq, [17](#)
  - mul\_eq, [17, 18](#)
  - negate, [18](#)
  - sub\_eq, [18](#)
- ndvec\_setfuncs
  - set, [16](#)
- negate
  - ndvec\_opeq, [18](#)
- Normalize vectors, [11](#)
- print\_on
  - mat\_io, [10](#)
  - ndvec\_io, [23](#)
  - vec\_io, [15](#)
- set
  - ndvec\_setfuncs, [16](#)
  - vec\_set\_comp, [10, 11](#)
- Set functions, [16](#)
- Set vector components, [10](#)
- sub
  - ndvec\_mathop, [21, 22](#)
- sub\_eq
  - ndvec\_opeq, [18](#)
- Tests for normality, orthogonality, [12](#)
- unitize
  - vec\_norm, [11](#)
- value\_type
  - vm\_V3Math, [27](#)
  - vm\_VMath, [29](#)
- vec\_dot\_cross
  - cross, [14](#)
  - dot, [14](#)
- vec\_io
  - cprint\_on, [15](#)
  - print\_on, [15](#)
- vec\_norm
  - unitize, [11](#)
- vec\_set\_comp
  - set, [10, 11](#)
- vec\_test\_norm
  - are\_orthogonal, [12](#)
  - are\_orthonormal, [12](#)
  - is\_unit\_vector, [13](#)
- vm\_M3Math, [24](#)
- vm\_M3Math common numerical operations, [5](#)
- vm\_math/ Directory Reference, [24](#)
- vm\_V3Math, [26](#)
  - value\_type, [27](#)
- vm\_V3Math common numerical operations, [5](#)
- vm\_VMath, [28](#)
  - value\_type, [29](#)
- vm\_VMath common numerical operations, [5](#)